

Compact Policy Routing

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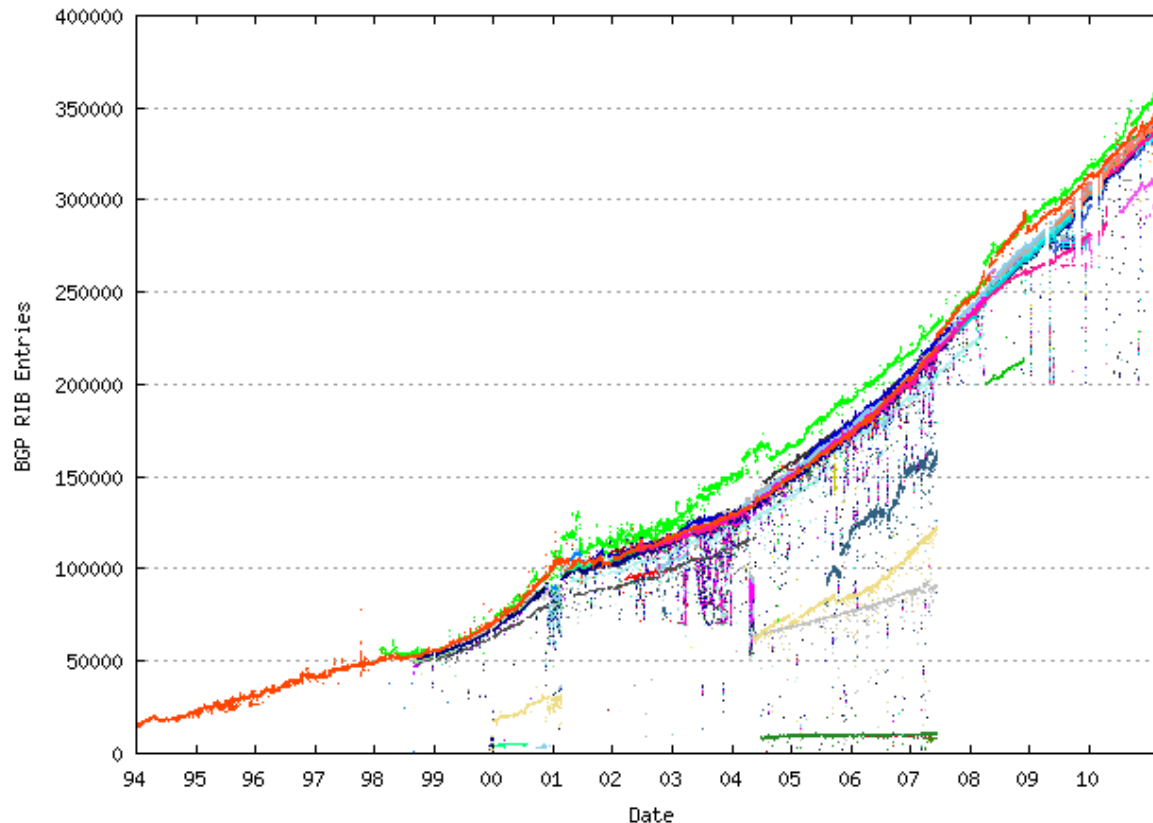
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Routing tables in the Internet grow rapidly



- There are many operational reasons behind this
- Are there any deep theoretical reasons as well?
- What can we do about it?

Compact routing and the Internet

- The theory dealing with fundamental routing scalability is called **compact routing**
- All our scalability results are for shortest paths
- But **Internet routing does not use shortest-paths**
- Instead, it is business interests, political pursuits and other operational concerns that shape Internet paths
 - business relations and SLA-s (BGP)
 - reliability and resilience (constraint-based routing)
 - available bandwidth (QoS routing, traffic engineering)
- Commonly called **policy routing**

This talk

- How do different policy routing architectures scale?
 - define a generic model for policy routing
 - characterize the memory requirements for implementing the models
 - discover the memory size–stretch trade-off
 - obtain tight bounds for policies important in practice

Routing algebras

- Abstract away **weight composition** (\oplus) and **weight comparison** (\preceq)
- A routing algebra $\mathcal{A} = (W, \phi, \oplus, \preceq)$ is a totally ordered commutative semigroup (Sobrinho, Griffin)
- Given a path $p = (v_1, v_2, \dots, v_k)$, the weight $w(p)$ of p is
$$w(p) = \bigoplus_{i=1}^{k-1} w(v_i, v_{i+1})$$
- A **preferred** $s - t$ **path** p^* over \mathcal{A} is the one with the smallest weight: $p^* : w(p^*) \preceq w(p), \forall p \in \mathcal{P}_{st}$
- Examples
 - shortest-path routing: $\mathcal{S} = (\mathbb{R}^+, \infty, +, \leq)$
 - widest-path routing: $\mathcal{W} = (\mathbb{R}^+, 0, \min, \geq)$
 - most-reliable-path routing: $\mathcal{R} = ((0, 1], 0, *, \geq)$
 - various sorts of BGP policies

Composing algebras

- Given two routing algebras \mathcal{A} and \mathcal{B}

$$\mathcal{A} = (W_{\mathcal{A}}, \phi_{\mathcal{A}}, \oplus_{\mathcal{A}}, \preceq_{\mathcal{A}}) \quad \text{and} \quad \mathcal{B} = (W_{\mathcal{B}}, \phi_{\mathcal{B}}, \oplus_{\mathcal{B}}, \preceq_{\mathcal{B}}) ,$$

their **lexicographic product** $\mathcal{A} \times \mathcal{B} = (W, \phi, \oplus, \preceq)$:

$$W = W_{\mathcal{A}} \times W_{\mathcal{B}}$$

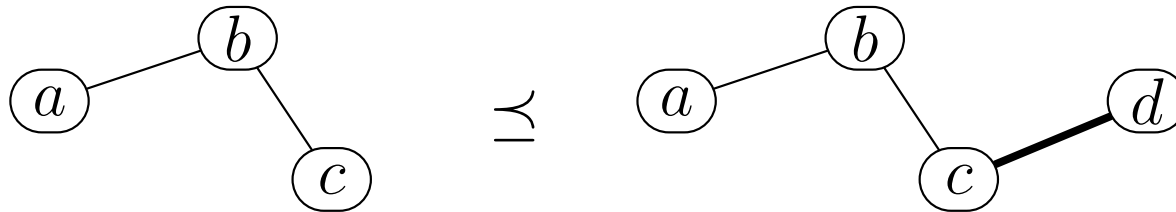
$$(w_1, v_1) \oplus (w_2, v_2) = (w_1 \oplus_{\mathcal{A}} w_2, v_1 \oplus_{\mathcal{B}} v_2)$$

$$(w_1, v_1) \preceq (w_2, v_2) = \begin{cases} v_1 \preceq_{\mathcal{B}} v_2 & \text{if } w_1 =_{\mathcal{A}} w_2 \\ w_1 \preceq_{\mathcal{A}} w_2 & \text{otherwise} \end{cases}$$

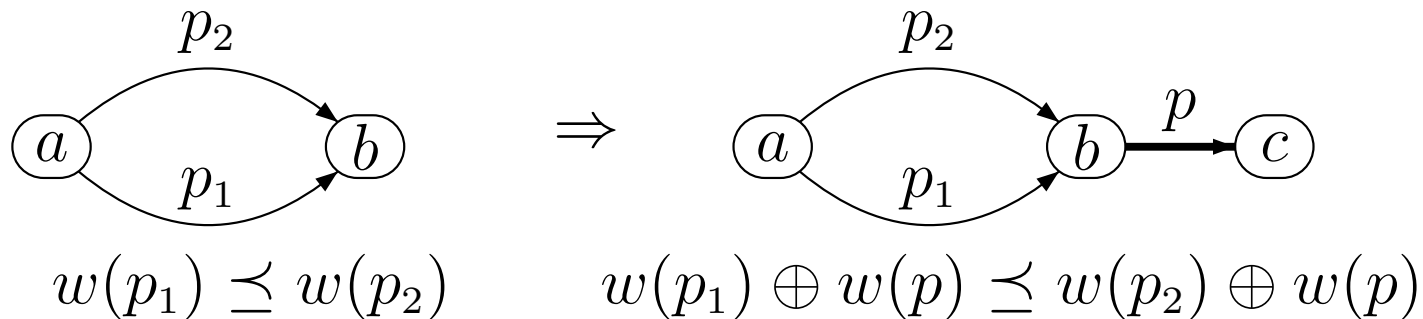
- Examples
 - widest-shortest path: $\mathcal{WS} = \mathcal{S} \times \mathcal{W}$
 - shortest-widest path: $\mathcal{SW} = \mathcal{W} \times \mathcal{S}$

Some useful algebraic properties

- A routing algebra \mathcal{A} is **regular**, if it is both
 - **monotone** (M): $w_1 \preceq w_2 \oplus w_1$ for all $w_1, w_2 \in W$, and



- **isotone** (I): $w_1 \preceq w_2 \Rightarrow w_3 \oplus w_1 \preceq w_3 \oplus w_2$ for all $w_1, w_2, w_3 \in W$



- Strict versions exist with \prec instead of \preceq

Routing process model

- The **local memory requirement** for implementing \mathcal{A} is

$$M_{\mathcal{A}} = \max_{G \in \mathcal{G}_n} \min_{R \in \mathcal{R}} \max_{u \in V} M_{\mathcal{A}}(R, u) \ ,$$

where $M_{\mathcal{A}}(R, u)$ is the number of bits needed to encode the local routing function R_u at some node u

- \mathcal{A} is **incompressible** if there is at least one graph in which at least one node needs linear information for routing according to \mathcal{A} , i.e., $M_{\mathcal{A}}$ is $\Omega(n)$
- **Compressible** otherwise

Propositions

- **Proposition:** a routing policy \mathcal{A} can be implemented by a destination-based routing function on any graph, if and only if it is **regular** (Sobrinho)
- Gives a trivial upper bound for regular algebras: if \mathcal{A} is regular then $M_{\mathcal{A}}$ is $O(n \log d)$
- Question is, whether this trivial bound is tight
- **Proposition:** $\mathcal{S} = (\mathbb{R}^+, \infty, +, \leq)$ is incompressible (Fraigniaud, Gavoille, Pérennès)
- First, we ask whether similar characterization exists for other algebras

Local memory requirements

- Policies with „maximum-type” weight composition scale well
- **Def.:** \mathcal{A} is **selective**, if $w_1 \oplus w_2 \in \{w_1, w_2\}$ for each $w_1, w_2 \in W$
- **Theorem:** if \mathcal{A} is selective and monotone, then it is compressible
- Under the above conditions, a spanning tree exists in which the only path between any s and t is a preferred $s - t$ path
- On the other hand, „shortest-path-like” policies do not scale
- **Theorem:** if \mathcal{A} is strictly monotone, then it is incompressible
- In fact, it is enough if \mathcal{A} contains a subalgebra isomorphic to shortest path routing

Local memory requirements

Algebra	Definition	Prop.	$M_{\mathcal{A}}$
Shortest path	$\mathcal{S} = (\mathbb{R}^+, \infty, +, \leq)$	SM, I	$\Theta(n)$
Widest path	$\mathcal{W} = (\mathbb{R}^+, 0, \min, \geq)$	S, I, M	$\Theta(\log n)$
Most reliable path	$\mathcal{R} = ((0, 1], 0, *, \geq)$	SM, I	$\Theta(n)$
Usable path	$\mathcal{U} = (\{1\}, 0, *, \geq)$	S, I, M	$\Theta(\log n)$
Widest-shortest path	$\mathcal{WS} = \mathcal{S} \times \mathcal{W}$	SM, I	$\Theta(n)$
Shortest-widest path	$\mathcal{SW} = \mathcal{W} \times \mathcal{S}$	SM, $\neg I$	$\Omega(n)$
BGP valley-free	\mathcal{B}_1	S	$\Theta(\log n)$
BGP local pref.	\mathcal{B}_2	$\neg M, \neg I$	$\Theta(n)$
BGP AS path length	\mathcal{B}_3	$\neg M, \neg I$	$\Theta(n)$

- Tight bounds for all regular algebras
- For \mathcal{SW} , all we know is that $M_{\mathcal{SW}}$ is $\Omega(n)$ and $O(n^2)$
- BGP policy routing is incompressible, even for a very minimalistic model

Algebraic compact routing

- Many important policies turn out incompressible
- With shortest path routing, a standard trick to decrease worst-case memory size is to allow routes to be somewhat longer
- Path length increase is upper bounded by some constant **stretch**
- Can we play out the same trick for policy routing?
- **Def.:** a routing scheme is of stretch k over algebra \mathcal{A} , if for any path p_{st} selected by the scheme:

$$w(p_{st}) \preceq \underbrace{w(p_{st}^*) \oplus w(p_{st}^*) \oplus \dots \oplus w(p_{st}^*)}_{k \text{ times}},$$

where p_{st}^* is some preferred $s - t$ path in \mathcal{A}

Algebraic compact routing

- Regular algebras admit a compact implementation
- **Theorem:** if \mathcal{A} is regular, then there is a stretch-3 compact routing scheme for \mathcal{A}
- Basically, we can generalize landmark-based compact routing schemes to regular algebras
- Local memory is $O(n^{2/3})$ (due to Cowen) or $O(n^{1/2})$ (Thorup and Zwick)

Algebraic compact routing

- What can we say when regularity fails?
- Turns out, when isotonicity fails in a particular way no compact implementation with constant stretch exists
- **Theorem:** if a monotone algebra \mathcal{A} contains a set of $p \geq 2$ weights $\{w_1, w_2, \dots, w_p\}$:

$$\forall i, j \in \{1, \dots, p\}, i \neq j : w_i \oplus w_j \succ w_i^{2k} \text{ and } w_i \oplus w_j \succ w_j^{2k}$$

for some $k \geq 1$, then there is no stretch- k routing scheme with sublinear memory requirement

- **Corollary:** no constant stretch compact routing scheme exists for shortest-widest path routing

Conclusions

- Scaling limits for shortest path routing well researched
- But shortest path routing does not matter in the Internet
- The fundamental scalability of policy routing has so far not been studied
- We took the first steps in this direction
 - gave an algebraic compressibility characterization
 - identified the algebraic requirements for effectively trading between path preference and memory
 - classified most practically relevant policies
- The main message is that with regularity, we are on the safe side, but when regularity fails, we might not even hope for a constant stretch compact routing algorithm
- Are there any theoretical reasons behind the recent explosion of routing table sizes? Answer seems affirmative