

The Dual Simplex Algorithm: A Summary

*WARNING: this is just a summary of the material covered in the full slide-deck **The Dual Simplex Algorithm** that will orient you as per the topics covered there; you are required to learn the full version, not just this summary!*

- Primal optimal (dual feasible) and primal feasible (dual optimal) bases
- The dual simplex tableau, dual optimality and the dual pivot rules
- Lots of exercises (in the slide-deck)

Recall: Linear Programming Duality

- Consider the (primal) maximization (linear) program:

$$\begin{aligned} z = \max \quad & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} \quad & \mathbf{A}\mathbf{x} = \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0} \end{aligned}$$

where \mathbf{A} is an $m \times n$ matrix, \mathbf{b} is a column m -vector, \mathbf{x} is a column n -vector, and \mathbf{c}^T is a row n -vector

- The dual is a standard form minimization problem, where \mathbf{w}^T is a row m -vector and \mathbf{v}^T is a row n -vector

$$\begin{aligned} \min \quad & \mathbf{w}^T \mathbf{b} \\ \text{s.t.} \quad & \mathbf{w}^T \mathbf{A} - \mathbf{v}^T = \mathbf{c}^T \\ & \mathbf{v}^T \geq \mathbf{0}, \mathbf{w}^T \text{ arbitrary} \end{aligned}$$

Strong Duality: Another Approach

- Let B be an *any* basis, let $x = \begin{bmatrix} x_B \\ x_N \end{bmatrix} = \begin{bmatrix} B^{-1}b \\ 0 \end{bmatrix}$ be the corresponding solution in the primal, and choose the dual variables as follows:

$$w^T = c_B^T B^{-1}, \quad v^T = \left[\underbrace{0}_{\text{basic}} \quad \underbrace{c_B^T B^{-1} N - c_N^T}_{\text{nonbasic}} \right]$$

- We can show that this choice satisfies the dual conditions at least partially
- First, the objective function value of the dual **identically** equals the primal objective function value in the basis B :

$$w^T b = c_B^T B^{-1} b = c_B^T x_B = c^T x$$

Strong Duality: Another Approach

- Second, the dual condition $w^T A - v^T = c^T$ also holds with identity:

$$\begin{aligned}w^T A - v^T &= c_B^T B^{-1} [B \quad N] - [0 \quad (c_B^T B^{-1} N - c_N^T)] \\ &= [c_B^T \quad (c_B^T B^{-1} N - c_B^T B^{-1} N + c_N^T)] = c^T\end{aligned}$$

- The only dual condition that may not hold is $v^T \geq 0$
- It is easy to show that this condition holds if and only if B is an optimal basis
- This is because in $v^T = [0 \quad (c_B^T B^{-1} N - c_N^T)]$ the component $c_B^T B^{-1} N - c_N^T$ coincides with row 0 of the optimal simplex table
- But this must be non-negative for an optimal simplex table, so we have $v^T \geq 0$ as required

The Dual Simplex Method

- We could say that **the primal simplex method develops a basis that satisfies all the dual conditions simultaneously**
- In each iteration it uniquely determines the value of the dual variables w^T and v^T so that
 - the dual objective function value equals the primal objective function value: $w^T b \equiv c^T x$
 - the dual condition $w^T A - v^T \equiv c^T$ identically holds
- In addition, at optimality it also satisfies the dual non-negativity conditions $v^T \geq 0$
- The **dual simplex method** is the “dual” of the primal simplex: it converges through a series of “dual feasible” bases into a “dual optimal” (primal feasible) basis
 - in every iteration it fulfills (D), (CS) and (P) partially
 - optimality when (P) is fully satisfied

The Dual Simplex Method

- Consider the standard form linear program:

$$\begin{aligned} \max \quad & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} \quad & \mathbf{Ax} = \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0} \end{aligned}$$

where \mathbf{A} is an $m \times n$ matrix, \mathbf{b} is a column m -vector, \mathbf{x} is a column n -vector, and \mathbf{c}^T is a row n -vector

- Let \mathbf{B} be a basis that satisfies
 - the primal optimality conditions (i.e., **dual feasible**)

$$\mathbf{c}_B^T \mathbf{B}^{-1} \mathbf{N} - \mathbf{c}_N^T \geq \mathbf{0}$$

- but is not primal feasible (i.e., not **dual optimal**)

$$\mathbf{B}^{-1} \mathbf{b} \not\geq \mathbf{0}$$

The Dual Simplex Method

- The simplex tableau for basis B
 - (dual) feasible if $\forall j \in N : z_j \geq 0$
 - (dual) optimal, if $\forall i \in \{1, \dots, m\} : \bar{b}_i \geq 0$
- The goal is to obtain a simplex tableau that is dual optimal, maintaining dual feasibility along the way
- In terms of the tableau, this means that
 - in row 0 we always have nonnegative elements (dual feasibility)
 - but the RHS column may contain negative elements (not dual optimal)
- Eventually, the RHS column will also become nonnegative
- This is attained through a sequence of (dual) pivots
- For brevity, we merely state the method without proofs

The Dual Simplex Method

- Choose the **leaving variable** x_r first as the basic variable with the smallest value in the current basis:

$$r = \operatorname{argmin}_{i \in \{1, \dots, m\}} \bar{b}_i$$

- **Lemma:** after the pivot we obtain a primal optimal basic feasible solution (row 0 is nonnegative), if the **entering variable** x_k is chosen according to:

$$k = \operatorname{argmin}_{j \in N} \left\{ -\frac{z_j}{y_{rj}} : y_{rj} < 0 \right\}$$

- **Lemma:** if $\forall j \in N : y_{rj} \geq 0$, then the dual is unbounded and the primal is infeasible
- Pivot on row r and column k

The Dual Simplex Method: Example

- Consider the linear program

$$\begin{array}{llllll} \min & 2x_1 & + & 3x_2 & + & 4x_3 \\ \text{s.t.} & x_1 & + & 2x_2 & + & x_3 & \geq & 3 \\ & 2x_1 & - & x_2 & + & 3x_3 & \geq & 4 \\ & x_1, & & x_2, & & x_3 & \geq & 0 \end{array}$$

- Bringing to standard form and converting to maximization (note the eventual inversion!):

$$\begin{array}{llllllllll} \max & -2x_1 & - & 3x_2 & - & 4x_3 & & & & & \\ \text{s.t.} & x_1 & + & 2x_2 & + & x_3 & - & x_4 & & & = & 3 \\ & 2x_1 & - & x_2 & + & 3x_3 & & & - & x_5 & = & 4 \\ & x_1, & & x_2, & & x_3, & & x_4, & & x_5 & \geq & 0 \end{array}$$

- Cannot use the primal simplex since the initial basis formed by the slack variables is not (primal) feasible

The Dual Simplex Method: Example

- Let us use the dual simplex (after inverting the constraints):

$$\begin{array}{rcllclclclcl}
 \max & -2x_1 & - & 3x_2 & - & 4x_3 & & & & & \\
 \text{s.t.} & -x_1 & - & 2x_2 & - & x_3 & + & x_4 & & & = & -3 \\
 & -2x_1 & + & x_2 & - & 3x_3 & & & + & x_5 & = & -4 \\
 & x_1, & & x_2, & & x_3, & & x_4, & & x_5 & \geq & 0
 \end{array}$$

- We can do this since the slack variables for a primal optimal (dual feasible) initial basis

$$\mathbf{c}_B^T \mathbf{B}^{-1} \mathbf{N} - \mathbf{c}_N^T = \mathbf{0} - [-2 \ -3 \ -4] \geq \mathbf{0}$$

- Not dual optimal: $\mathbf{B}^{-1} \mathbf{b} = \mathbf{I}_2 \begin{bmatrix} -3 \\ -4 \end{bmatrix} = \begin{bmatrix} -3 \\ -4 \end{bmatrix} \not\geq \mathbf{0}$

The Dual Simplex Method: Example

- The initial simplex tableau:

	z	x_1	x_2	x_3	x_4	x_5	RHS
z	1	2	3	4	0	0	0
x_4	0	-1	-2	-1	1	0	-3
x_5	0	-2	1	-3	0	1	-4

- The most negative basic variable leaves the basis: x_5
- The entering variable is x_1 as $-\frac{z_1}{y_{51}} = \min\left\{-\frac{z_j}{y_{5j}} : y_{5j} < 0\right\}$
- Divide the j -th element of row 0 with the j -th element of the r -th row if that is negative and invert, and take the minimum
- If we choose the leaving and entering variable this way, we get a dual feasible basis after the pivot

The Dual Simplex Method: Example

	z	x_1	x_2	x_3	x_4	x_5	RHS
z	1	2	3	4	0	0	0
x_4	0	-1	-2	-1	1	0	-3
x_1	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	0	$-\frac{1}{2}$	2

	z	x_1	x_2	x_3	x_4	x_5	RHS
z	1	2	3	4	0	0	0
x_4	0	0	$-\frac{5}{2}$	$\frac{1}{2}$	1	$-\frac{1}{2}$	-1
x_1	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	0	$-\frac{1}{2}$	2

	z	x_1	x_2	x_3	x_4	x_5	RHS
z	1	0	4	1	0	1	-4
x_4	0	0	$-\frac{5}{2}$	$\frac{1}{2}$	1	$-\frac{1}{2}$	-1
x_1	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	0	$-\frac{1}{2}$	2

The Dual Simplex Method: Example

- The new basis is dual feasible (primal optimal) but still not dual optimal, as $x_4 = -1 < 0$
- x_4 leaves the basis and $x_2 = \operatorname{argmin}\{-\frac{z_j}{y_{4j}} : y_{4j} < 0\}$ enters

	x_1	x_2	x_3	x_4	x_5	RHS
z	0	0	$\frac{9}{5}$	$\frac{8}{5}$	$\frac{1}{5}$	$-\frac{28}{5}$
x_2	0	1	$-\frac{1}{5}$	$-\frac{2}{5}$	$\frac{1}{5}$	$\frac{2}{5}$
x_1	1	0	$\frac{7}{5}$	$-\frac{1}{5}$	$-\frac{2}{5}$	$\frac{11}{5}$

- The resultant basis is both dual optimal and dual feasible
- The optimum for the maximization problem is $z = -\frac{28}{5}$, attained at the point $\mathbf{x} = [\frac{11}{5} \quad \frac{2}{5} \quad 0]^T$

The Dual Simplex Method: Example

- Observe that the objective function value for the maximization problem has decreased in each iteration

$$\max -2x_1 - 3x_2 - 4x_3 : 0 \rightarrow -4 \rightarrow -\frac{28}{5}$$

- Of course, this is because we have in fact solved the dual minimization problem $\min\{\mathbf{w}^T \mathbf{b} : \mathbf{w}^T \mathbf{A} \geq \mathbf{c}^T\}$
- Choosing $\mathbf{w}^T = \mathbf{c}_B \mathbf{B}^{-1}$ the dual objective function $\mathbf{w}^T \mathbf{b} = \mathbf{c}_B \mathbf{B}^{-1} \mathbf{b}$ can be read from the simplex tableau in each step (row zero, RHS column)

$$\min \mathbf{w}^T \mathbf{b} : 0 \rightarrow -4 \rightarrow -\frac{28}{5}$$

- Originally we had a minimization problem (invert!), whose optimum is thus $z = \frac{28}{5}$